

Milestone Review Flysheet

Please see Milestone Review Flysheet Instructions.

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| Institution | University of Louisville |
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| Milestone | PDR |
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| Vehicle Properties | |
|----------------------------|------------------------|
| Total Length (in) | 143 |
| Diameter (in) | 6.17 |
| Gross Lift Off Weight (lb) | 38.3 |
| Airframe Material | Carbon fiber |
| Fin Material | Fiberglass |
| Drag | Drag coefficient: 0.45 |

| Motor Properties | |
|---------------------------|-------------|
| Motor Manufacturer(s) | Cesaroni |
| Motor Designation(s) | L935-IM |
| Max/Average Thrust (lb) | 356.5/209.9 |
| Total Impulse (lbf-sec) | 707.4 |
| Mass (before, after burn) | 5.6, 1.8 |
| Liftoff Thrust (lb) | 148.4 |

| Stability Analysis | |
|-----------------------------------|-------|
| Center of Pressure (in from nose) | 99.61 |
| Center of Gravity (in from nose) | 87.35 |
| Static Stability Margin | 1.99 |
| Thrust-to-Weight Ratio | 5.48 |
| Rail Size (in)/ Length (in) | 120 |
| Rail Exit Velocity (ft/s) | 66.2 |

| Ascent Analysis | | |
|--|------|--|
| Maximum Velocity (ft/s) | 471 | |
| Maximum Mach Number | 0.42 | |
| Maximum Acceleration (ft/s ²) | 248 | |
| Target Apogee (1st Stage if Multiple Stages) | 3431 | |
| Stable Velocity (ft/s) | 60 | |
| Distance to Stable Velocity (ft) | 8.5 | |

| Recovery System Properties | | | | |
|---|----------------------------|--------------------------------|-----------|-----------|
| Upper Airframe Parachute | | | | |
| Manufacturer/Model | | Vortex Ring - custom made | | |
| Size | | 4.7 ft ² | | |
| Altitude at Deployment (ft) | | 3000 | | |
| Velocity at Deployment (ft/s) | | 64.4 | | |
| Terminal Velocity (ft/s) | | 18.4 | | |
| Recovery Harness Material | | 9/16" tubular nylon | | |
| Harness Size/Thickness (in) | | 9/16" | | |
| Recovery Harness Length (ft) | | 30 | | |
| Harness/Airframe Interfaces | | 1/4 inch U-bolt and quick link | | |
| Kinetic Energy of Each Section (ft-lbs) | Section 1 (Upper Airframe) | Section 2 | Section 3 | Section 4 |
| | 60 | | | |

| Recovery System Properties | | | | |
|---|----------------------------|--------------------------------|-----------|-----------|
| Lower Airframe Parachute | | | | |
| Manufacturer/Model | | Cruciform - custom made | | |
| Size | | 8.6 ft ² | | |
| Altitude at Deployment (ft) | | 1250 | | |
| Velocity at Deployment (ft/s) | | 34.19 | | |
| Terminal Velocity (ft/s) | | 16.73 | | |
| Recovery Harness Material | | 9/16" tubular nylon | | |
| Harness Size/Thickness (in) | | 9/16" | | |
| Recovery Harness Length (ft) | | 25 | | |
| Harness/Airframe Interfaces | | 1/4 inch U-bolt and quick link | | |
| Kinetic Energy of Each Section (ft-lbs) | Section 1 (Lower Airframe) | Section 2 (Cache Capsule) | Section 3 | Section 4 |
| | 60 | 30 | | |

| Recovery Electronics | |
|------------------------------------|--|
| Altimeter(s)/Timer(s) (Make/Model) | PerfectFlite StratoLogger (x5) Telemetrum v2.9 (x1) |
| Redundancy Plan | Each avionics bay will have a StratoLogger as a back up altimeter. The upper and lower airframes utilize a StratoLogger as a primary altimeter while the cache capsule uses a TeleMetrum as the primary. |

| Recovery Electronics | |
|--|-----------------------|
| Rocket Locators (Make/Model) | Garmin Astro DC 40 |
| Transmitting Frequencies | ***Required by CDR*** |
| Black Powder Mass Upper Airframe Chute (grams) | 4 |

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| Pad Stay Time (Launch Configuration) | 1 hour |
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|---|---|
| Black Powder Lower Airframe Chute (grams) | 4 |
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Autonomous Ground Support Equipment (AGSE)

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| | Overview |
| Capture Mechanism | A threadless screw will move down the height of the ground station where two gripper arms will grab the payload. From there, they will raise to system height, the rod rotates 90 degrees and then inserts the payload into the vehicle. |
| | Overview |
| Container Mechanism | The cache will be inserted into two clips, located inside the capsule. The clips mechanically retain the capsule. The doors to the capsule are actuated via servo, further retaining the door. |
| | Overview |
| Launch Rail Mechanism | The rail will not be locked in place, instead, a screw mechanism will guide the tower to the proper position. A motor will monitor and provide necessary torque to keep the platform at the 5 degree of vertical position as stated from the statement of work. |
| | Overview |
| Igniter Installation Mechanism | The igniter will be augmented with dowel rods and aluminum tape for shielding. Four wheels will extend the igniter wire until it is in the proper placement in the vehicle. A magnetic field sensor will detect a magnetic flag on the wire to ensure proper placement. |
| CG Location of Launch Pad (in inches) When Rail is Horizontal (Use Base of Rail as the Reference Point) | |
| Moment Analysis | Vehicle horizontal: 10.9310 inches. Vehicle in launch position: 35.8407 |

Payload

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| | Overview |
| Payload 1 | Custom weather sensing (wind speed, wind direction, and temperature) will be placed on the ground station to get a gradient of conditions that would effect flight. This data will be transmitted via bluetooth communications to the vehicle during flight to be recovered with the cache system. |
| | Overview |
| Payload 2 | N/A |

Test Plans, Status, and Results

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|------------------------|--|
| Ejection Charge Tests | All ejection charges will be tested on the ground prior to flight to ensure that black powder charges are all properly sized. |
| Sub-scale Test Flights | One half scale aerodynamic test. Flying above 3000 ft to test bluetooth range. A subscale vortex ring will also be flown in recovery to validate design. |

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| Full-scale Test Flights | Multiple tests are planned to validate all systems on board. |
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Additional Comments

